

SwissCube Project Phase D, November 11th 2008

## **SwissCube**

# Science Mission and Payload Design

Noémy Scheidegger





0.00

## **Science Objectives**

Measure the airglow emission in the upper atmosphere at 100 km altitude to :

- Demonstrate the feasibility of using airglow as a basis for a low-cost earth sensor
- Validate the established airglow model or bring additional information about airglow dependence on
  - $\rightarrow$  latitude
  - $\rightarrow$  altitude
  - $\rightarrow$  local solar time



nightglow and aurora borealis











\* \* \*\*

## Aiglow Model



**Hes**∙so

ÉCOLE POLYTECHNIQUE Fédérale de Lausanne Haute Ecole Spécialisée de Suisse occidentale de Neuch

Université

November 11th 2008



## Driving Requirements for the SwissCube Payload

- Payload may be a technology demonstrator of an earth sensor based on airglow
  - Observes the emission at 762 nm with a bandwidth between 10 nm and 40 nm
  - Has a spatial resolution of at least 0.3° and a FOV of 20°
  - Can perform science mission with the sun no closer than 30° from its boresight.
- Physical and electrical constraints
  - Volume: 30 x 30 x 65 mm<sup>3</sup> for the optics
     80 x 35 x 15 mm<sup>3</sup> for the payload board
  - Mass: < 50 g
  - Peak Power: < 450 mW during 30 s for each image</li>
- Additional design driver
  - The PL board is not a critical element of the SwissCube satellite

 $\rightarrow$  no redundancy has been taken into account for this subsystem



#### optics of the AIRES earth sensor





## **Operational Scenario: Frequency of Measurements**

- During the first 3 month one image each 4.5 days:
  - 5 images of dayglow/nightglow measured at limb/nadir
  - Number of images limited by ground station coverage and relatively low data rate
  - Total: 20 measurements, cycle repetition of 18 days

- After 3 month: observation of variation of emission intensity depending on latitude
  - Dayglow/nightglow above 85° N/S
  - Dayglow/nightglow between 40° and 50° N/S
  - Dayglow/nightglow between 5° N and 5° S
  - Total : 10 measurements, cycle of repetition of 45 days
     8 measurements per latitude in one year





## Operational Scenario: Data Exploitation

- Data Products
  - Each image provides a measurement of the intensity of the phenomena
    - Range measured: [500 61400] photons
    - Resolution: 500 photons
  - Complementary information: time, latitude, solar local time, altitude
- Data Exploitation
  - Data will be used to validate model
  - Data will then be available to public and scientific institutions (interest from World Radiation Center in Davos/CH)
  - Space Weather relevance has not yet been assessed, will be done once data is received





## Operational Scenario: PL Board

- PL board always turned on for housekeeping
- Detector turned on only when science observations are carried out
- Science observations are triggered by EPS
- Power consumption:
  - 8 mW when no science observations are performed
  - < 450 mW during science observations</li>





## **Design Description: Overview**

#### CMOS detector MT9V032

188 x 120 pixels, pixel size = 24  $\mu$ m resolution = 0.16°/pixel FOV = 18.8 x 25°

#### focusing optics triplet design with OTS components

support structure titanium



first SwissCube payload prototype

#### baffle

solar exclusion angle =  $30^{\circ}$ attenuation factor =  $10^{-4}$ vanes: stainless steel spacers: aluminium

> closing cap aluminium

Université

filter CWL 767 nm FWHM 20 nm

#### payload board

microcontroller MSP430F1611 CMOS detector MT9V032 temperature sensor LM94022 oscillator HC-49/US SMD RAM R1LV0416CSB-7LI

November 11th 2008





0 00

## Design Description: Optical System

- Triplet design with off-the-shelf components
- FOV 18.8° x 25°
- Resolution 0.16°/pixel
- Baffle for a solar exclusion angle of 30° with an attenuation factor of 10<sup>-4</sup>
- Filter with a central wavelength at 767 nm and a bandwidth of 20 nm







## Design Description: Payload Electronics

- Microcontroller MSP430F1611
  - Operate the detector
  - Communicate with the EPS
  - Read temperature sensors
- CMOS Detector MT9V032

   Capture images of the airglow
- Temperature Sensor LM94022
  - Used for dark signal correction
- Oscillator HC-49/US SMD
  - Provide clock reference for the CMOS detector
- RAM R1LV0416CSB-7LI
  - Store images until transmission to ground station









## Design Description: Expected Airglow Images

#### Limb Observations



### Zenith Observations



Hes ⋅so

Université

